EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	811	(114/230.1,230.15,230.17,230.18,230. 19).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/07/26 10:56
L2	3	L1 and moor\$3 adj (arrangement system) and force and attachment and measur\$3 and control	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR .	ON	2007/07/26 10:46
L3	. 3	L1 and moor\$3 adj (arrangement system) and force and attachment and measur\$3 and control and robot	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR .	ON	2007/07/26 10:46
L4	7	moor\$3 adj (arrangement system) and force and attachment and measur\$3 and control and robot	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/07/26 10:46
L5	147	(method system arrangement) and moor\$3 and (vessel ship) and robot and (attract\$3 hold\$3) and force and (measur\$4 determin\$3 monitor\$3)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/07/26 11:07
L7	10	L1 and (method system arrangement) and moor\$3 and (vessel ship) and robot and (attract\$3 hold\$3) and force and (measur\$4 determin\$3 monitor\$3) and (engag\$4 fasten\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/07/26 11:14
L8	1	L1 and (method system arrangement) and moor\$3 and (vessel ship) and robot and ((attract\$3 hold\$3) adj force) and (measur\$4 determin\$3 monitor\$3) and (engag\$4 fasten\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON .	2007/07/26 11:15

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L9	3	(method system arrangement) and moor\$3 and (vessel ship) and robot and ((attract\$3 hold\$3) adj force) and (measur\$4 determin\$3 monitor\$3) and (engag\$4 fasten\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/07/26 11:17
L10	1	((method system arrangement) and moor\$3 and (vessel ship) and robot and ((attract\$3 hold\$3) adj force) and (measur\$4 determin\$3 monitor\$3) and (engag\$4 fasten\$4)).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/07/26 11:17